

CSC D70: Compiler Optimization Pointer Analysis

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*The content of this lecture is adapted from the lectures of
Todd Mowry, Greg Steffan, and Phillip Gibbons*

Outline

- **Basics**
- **Design Options**
- **Pointer Analysis Algorithms**
- **Pointer Analysis Using BDDs**
- **Probabilistic Pointer Analysis**

Pros and Cons of Pointers

- Many procedural languages have pointers
 - e.g., C or C++: `int *p = &x;`
- Pointers are powerful and convenient
 - can build arbitrary data structures
- Pointers can also hinder compiler optimization
 - hard to know where pointers are pointing
 - must be conservative in their presence
- Has inspired much research
 - analyses to decide where pointers are pointing
 - many options and trade-offs
 - open problem: a scalable accurate analysis

Pointer Analysis Basics: Aliases

- Two variables are **aliases** if:
 - they **reference the same memory location**
- More useful:
 - **prove variables reference different location**

```
int x,y;  
int *p = &x;  
int *q = &y;  
int *r = p;  
int **s = &q;
```

Alias Sets ?

```
{x, *p, *r}  
{y, *q, **s}  
{q, *s}
```

p and q point to different locs

The Pointer Alias Analysis Problem

- Decide for every pair of pointers at every program point:
 - do they point to the same memory location?
- A difficult problem
 - shown to be undecidable by Landi, 1992
- Correctness:
 - report all pairs of pointers which do/may alias
- Ambiguous:
 - two pointers which may or may not alias
- Accuracy/Precision:
 - how few pairs of pointers are reported while remaining correct
 - i.e., reduce ambiguity to improve accuracy

Many Uses of Pointer Analysis

- **Basic compiler optimizations**
 - register allocation, CSE, dead code elimination, live variables, instruction scheduling, loop invariant code motion, redundant load/store elimination
- **Parallelization**
 - instruction-level parallelism
 - thread-level parallelism
- **Behavioral synthesis**
 - automatically converting C-code into gates
- **Error detection and program understanding**
 - memory leaks, wild pointers, security holes

Challenges for Pointer Analysis

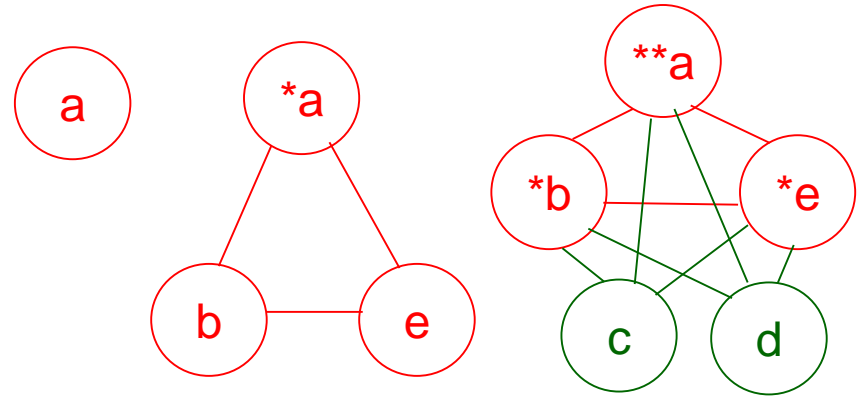
- **Complexity**: huge in **space** and **time**
 - compare every pointer with every other pointer
 - at every program point
 - potentially considering all program paths to that point
- **Scalability vs. accuracy trade-off**
 - different analyses motivated for different purposes
 - many useful algorithms (adds to confusion)
- **Coding corner cases**
 - pointer arithmetic (`*p++`), casting, function pointers, long-jumps
- **Whole program?**
 - most algorithms require the entire program
 - library code? optimizing at link-time only?

Pointer Analysis: Design Options

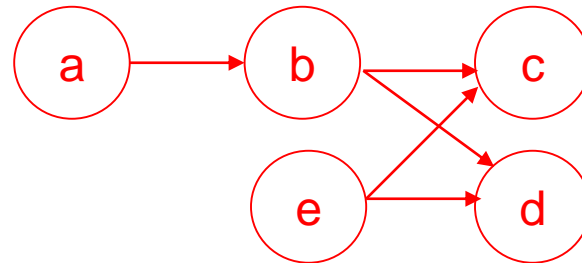
- Representation
- Heap modeling
- Aggregate modeling
- Flow sensitivity
- Context sensitivity

Alias Representation

- Track **pointer** aliases
 - $\langle *a, b \rangle, \langle *a, e \rangle, \langle b, e \rangle$
 $\langle **a, c \rangle, \langle **a, d \rangle, \dots$
 - More precise, less efficient



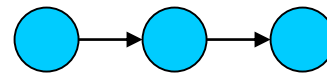
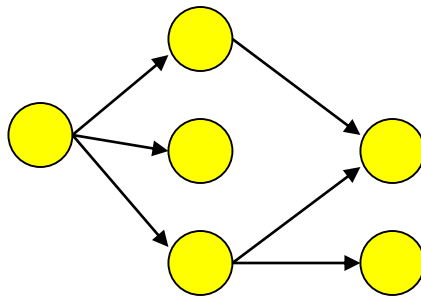
- Track **points-to** info
 - $\langle a, b \rangle, \langle b, c \rangle, \langle b, d \rangle,$
 $\langle e, c \rangle, \langle e, d \rangle$
 - Less precise, more efficient
 - Why?



```
a = &b;  
b = &c;  
b = &d;  
e = b;
```

Heap Modeling Options

- Heap merged
 - i.e. “no heap modeling”
- Allocation site (any call to malloc/calloc)
 - Consider each to be a unique location
 - Doesn't differentiate between multiple objects allocated by the same allocation site
- Shape analysis
 - Recognize linked lists, trees, DAGs, etc.



Aggregate Modeling Options

Arrays



Elements are treated as **individual locations**

or



Treat entire array as a **single location**

or



Treat **first element separate** from others

Structures



Elements are treated as **individual locations** (“field sensitive”)

or



Treat entire structure as a **single location**

What are the tradeoffs?

Flow Sensitivity Options

- **Flow insensitive**
 - The order of statements doesn't matter
 - Result of analysis is the same regardless of statement order
 - Uses a single global state to store results as they are computed
 - Not very accurate
- **Flow sensitive**
 - The order of the statements matter
 - Need a control flow graph
 - Must store results for each program point
 - Improves accuracy
- **Path sensitive**
 - Each path in a control flow graph is considered

Flow Sensitivity Example

(assuming allocation-site heap modeling)

```
S1: a = malloc(...);  
S2: b = malloc(...);  
S3: a = b;  
S4: a = malloc(...);  
S5: if(c)  
    a = b;  
S6: if(!c)  
    a = malloc(...);  
S7: ... = *a;
```

Flow Insensitive

$a_{S7} \rightarrow$ {heapS1, heapS2, heapS4, heapS6}

(order doesn't matter, union of all possibilities)

Flow Sensitive

$a_{S7} \rightarrow$ {heapS2, heapS4, heapS6}

(in-order, doesn't know s5 & s6 are exclusive)

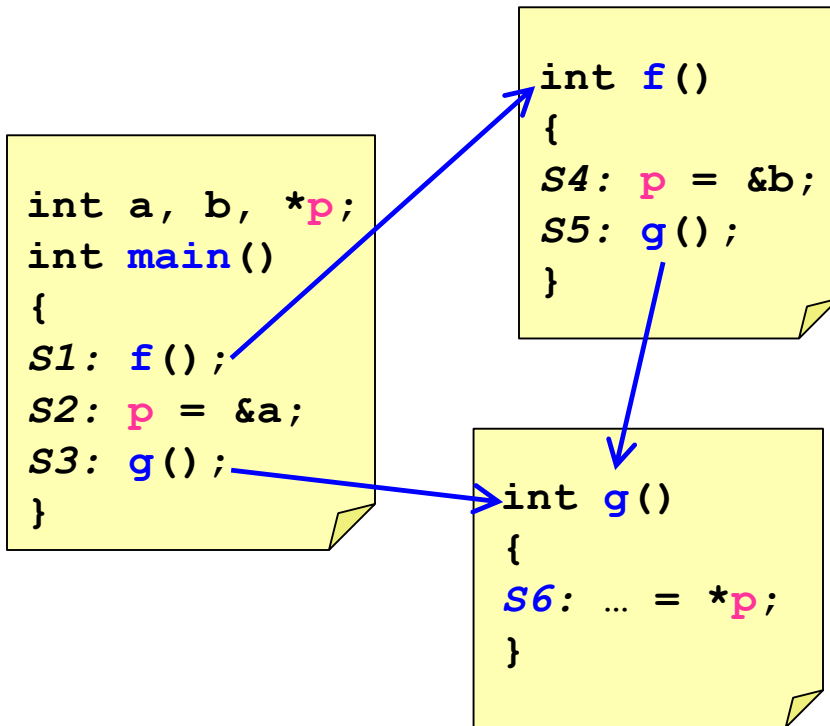
Path Sensitive

$a_{S7} \rightarrow$ {heapS2, heapS6}

(in-order, knows s5 & s6 are exclusive)

Context Sensitivity Options

- Context insensitive/sensitive
 - whether to consider **different calling contexts**
 - e.g., what are the possibilities for **p** at **S6**?



Context Insensitive:

$p_{S6} \Rightarrow \{a,b\}$

Context Sensitive:

Called from S5: $p_{S6} \Rightarrow \{b\}$

Called from S3: $p_{S6} \Rightarrow \{a\}$

Pointer Alias Analysis Algorithms

References:

- *“Points-to analysis in almost linear time”*, Steensgaard, POPL 1996
- *“Program Analysis and Specialization for the C Programming Language”*, Andersen, Technical Report, 1994
- *“Context-sensitive interprocedural points-to analysis in the presence of function pointers”*, Emami et al., PLDI 1994
- *“Pointer analysis: haven't we solved this problem yet?”*, Hind, PASTE 2001
- *“Which pointer analysis should I use?”*, Hind et al., ISSTA 2000
- ...
- *“Introspective analysis: context-sensitivity, across the board”*, Smaragdakis et al., PLDI 2014
- *“Sparse flow-sensitive pointer analysis for multithreaded programs”*, Sui et al., CGO 2016
- *“Symbolic range analysis of pointers”*, Paisanteet et al., CGO 2016

Address Taken

- Basic, fast, ultra-conservative algorithm
 - flow-insensitive, context-insensitive
 - often used in production compilers
- Algorithm:
 - Generate the set of all variables whose addresses are assigned to another variable.
 - Assume that any pointer can potentially point to any variable in that set.
- Complexity: $O(n)$ - linear in size of program
- Accuracy: very imprecise

Address Taken Example

```
T *p, *q, *r;

int main() {
S1: p = alloc(T);
    f();
    g(&p);
S4: p = alloc(T);
S5: ... = *p;
}
```

```
void f() {
S6: q = alloc(T);
    g(&q);
S8: r = alloc(T);
}
```

```
g(T **fp) {
    T local;
    if(...)
s9:    p = &local;
}
```

$P_{S5} = \{\text{heap_S1, p, heap_S4, heap_S6, q, heap_S8, local}\}$

Andersen's Algorithm

- Flow-insensitive, context-insensitive, iterative
- Representation:
 - one points-to graph for entire program
 - each node represents exactly one location
- For each statement, build the points-to graph:

$y = \&x$	y points-to x
$y = x$	if x points-to w then y points-to w
$*y = x$	if y points-to z and x points-to w then z points-to w
$y = *x$	if x points-to z and z points-to w then y points-to w

- Iterate until graph no longer changes
- Worst case complexity: $O(n^3)$, where n = program size

Andersen Example

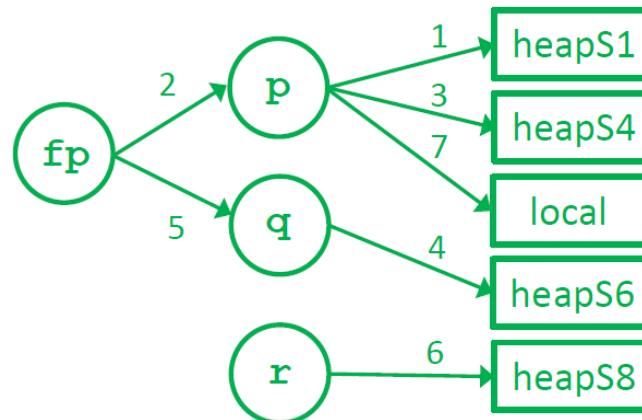
```
T *p, *q, *r;
```

```
int main() {  
S1: p = alloc(T);  
    f();  
    g(&p);  
S4: p = alloc(T);  
S5: ... = *p;  
}
```

```
void f() {  
S6: q = alloc(T);  
    g(&q);  
S8: r = alloc(T);  
}
```

```
g(T **fp) {  
    T local;  
    if(...)  
s9:    p = &local;  
}
```

$P_{S5} = \{\text{heap_S1}, \text{heap_S4}, \text{local}\}$



Steensgaard's Algorithm

- Flow-insensitive, context-insensitive
- Representation:
 - a **compact points-to** graph for entire program
 - each node can represent **multiple locations**
 - but **can only point to one other node**
 - i.e. every node has a **fan-out of 1 or 0**
- ***union-find*** data structure implements fan-out
 - “unioning” while finding **eliminates need to iterate**
- Worst case complexity: **$O(n)$**
- Precision: less precise than Andersen's

Steensgaard Example

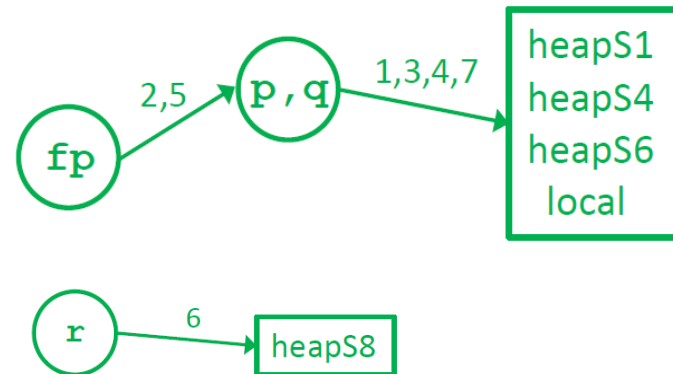
```
T *p, *q, *r;
```

```
int main() {  
S1: p = alloc(T);  
    f();  
    g(&p);  
S4: p = alloc(T);  
S5: ... = *p;  
}
```

```
void f() {  
S6: q = alloc(T);  
    g(&q);  
S8: r = alloc(T);  
}
```

```
g(T **fp) {  
    T local;  
    if(...)  
s9:    p = &local;  
}
```

$P_{S5} = \{\text{heap_S1},$
 $\text{heap_S4},$
 $\text{heap_S6},$
 $\text{local}\}$



Example with Flow Sensitivity

```
T *p, *q, *r;

int main() {
S1: p = alloc(T);
    f();
    g(&p);
S4: p = alloc(T);
S5: ... = *p;
}
```

```
void f() {
S6: q = alloc(T);
    g(&q);
S8: r = alloc(T);
}
```

```
g(T **fp) {
    T local;
    if(...)
s9:    p = &local;
}
```

$P_{S5} = \{\text{heap_s4}\}$

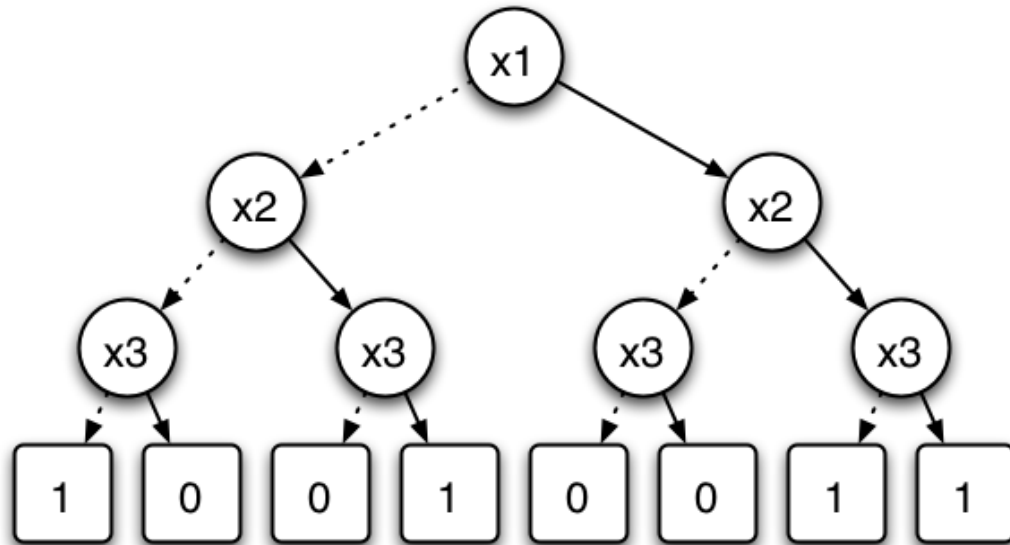
$P_{S9} = \{\text{local, heap_s1}\}$

Pointer Analysis Using BDDs

References:

- *“Cloning-based context-sensitive pointer alias analysis using binary decision diagrams”*, Whaley and Lam, PLDI 2004
- *“Symbolic pointer analysis revisited”*, Zhu and Calman, PDLI 2004
- *“Points-to analysis using BDDs”*, Berndt et al, PDLI 2003

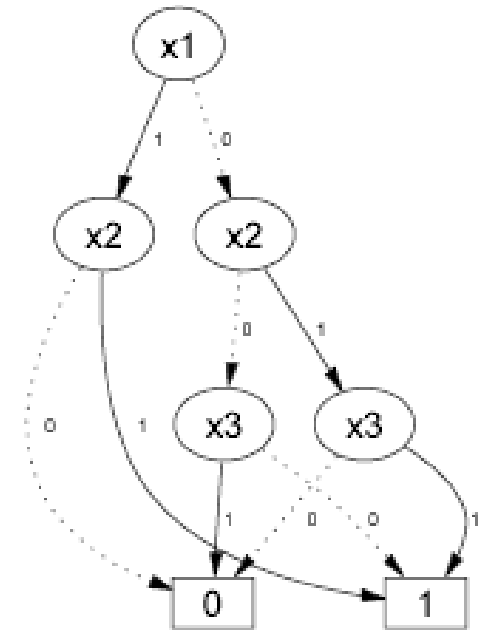
Binary Decision Diagram (BDD)



Binary Decision Tree

x_1	x_2	x_3	f
0	0	0	1
0	0	1	0
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	0
1	1	0	1
1	1	1	1

Truth Table



BDD

BDD-Based Pointer Analysis

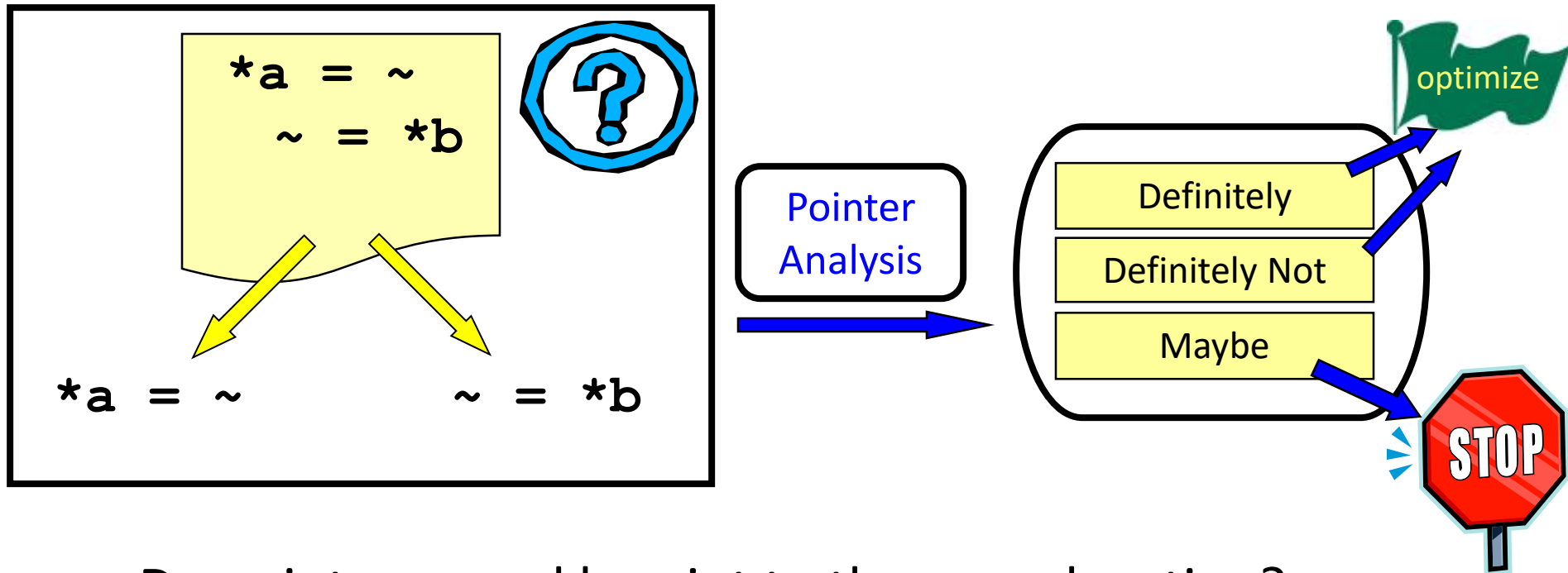
- Use a **BDD** to represent **transfer functions**
 - encode **procedure** as a **function of its calling context**
 - compact and efficient representation
- Perform **context-sensitive, inter-procedural** analysis
 - similar to dataflow analysis
 - but across the procedure call graph
- **Gives accurate results**
 - and **scales up to large programs**

Probabilistic Pointer Analysis

References:

- *“A Probabilistic Pointer Analysis for Speculative Optimizations”*, DaSilva and Steffan, ASPLOS 2006
- *“Compiler support for speculative multithreading architecture with probabilistic points-to analysis”*, Shen et al., PPOPP 2003
- *“Speculative Alias Analysis for Executable Code”*, Fernandez and Espasa, PACT 2002
- *“A General Compiler Framework for Speculative Optimizations Using Data Speculative Code Motion”*, Dai et al., CGO 2005
- *“Speculative register promotion using Advanced Load Address Table (ALAT)”*, Lin et al., CGO 2003

Pointer Analysis: Yes, No, & Maybe



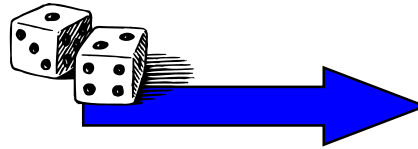
- Do pointers a and b point to the same location?
 - Repeat for every pair of pointers at every program point
- How can we optimize the “maybe” cases?

Let's Speculate



- Implement a **potentially unsafe** optimization
 - **Verify** and **Recover** if necessary

```
int *a, x;  
...  
while (...)  
{  
    x = *a;  
    ...  
}
```



a is *probably*
loop invariant

```
int *a, x, tmp;  
...  
tmp = *a;  
while (...)  
{  
    x = tmp;  
    ...  
}  
<verify, recover?>
```

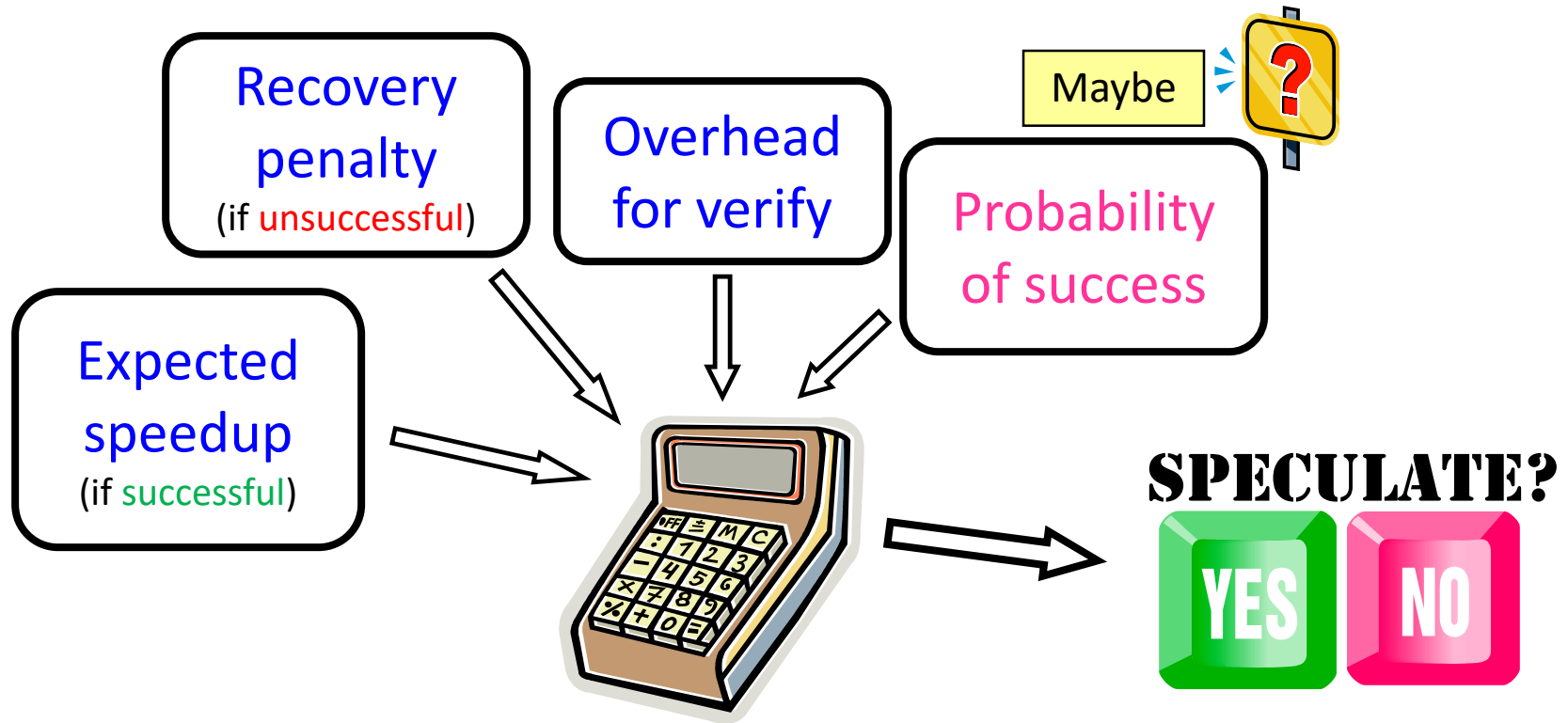
Data Speculative Optimizations

- EPIC Instruction sets
 - Support for speculative load/store instructions (e.g., Itanium)
- Speculative compiler optimizations
 - Dead store elimination, redundancy elimination, copy propagation, strength reduction, register promotion
- Thread-level speculation (TLS)
 - Hardware and compiler support for speculative parallel threads
- Transactional programming
 - Hardware and software support for speculative parallel transactions

Heavy reliance on detailed profile feedback

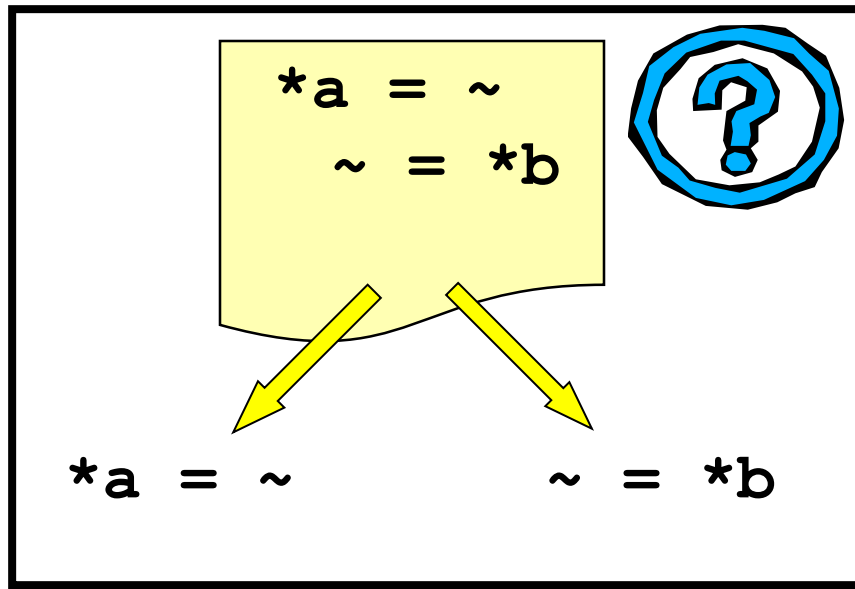
Can We Quantify “Maybe”?

- Estimate the potential benefit for speculating:

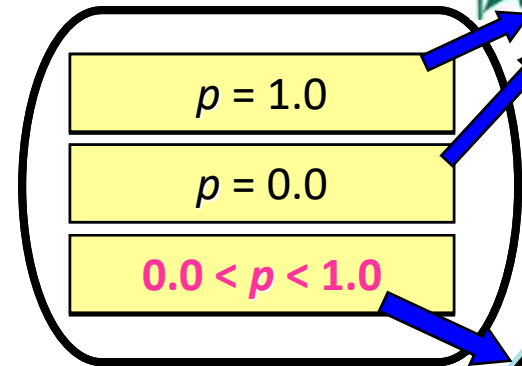


Ideally “maybe” should be a probability.

Conventional Pointer Analysis

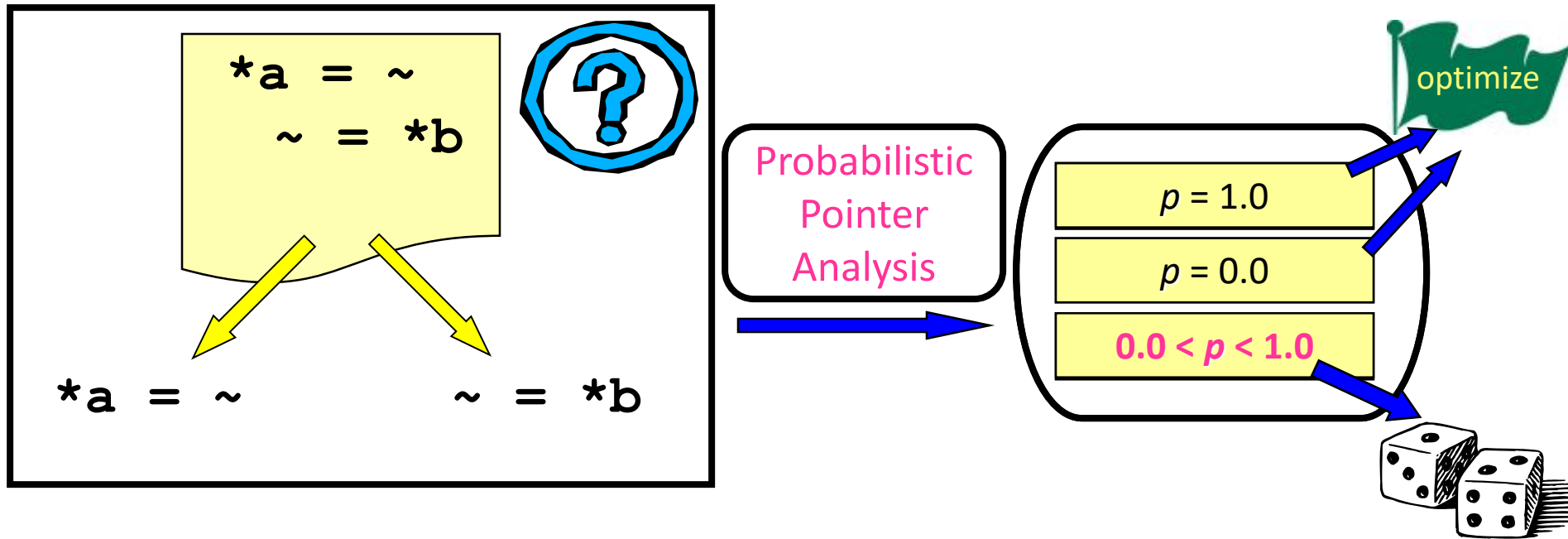


Pointer
Analysis



- Do pointers **a** and **b** point to the same location?
 - Repeat for every pair of pointers at every program point

Probabilistic Pointer Analysis



- Potential advantage of Probabilistic Pointer Analysis:
 - it doesn't need to be safe

PPA Research Objectives

- Accurate points-to probability information
 - at every static pointer dereference
- Scalable analysis
 - Goal: entire SPEC integer benchmark suite
- Understand scalability/accuracy tradeoff
 - through flexible static memory model

Improve our understanding of programs

Algorithm Design Choices

Fixed:

- Bottom Up / Top Down Approach
- Linear transfer functions (for scalability)
- One-level context and flow sensitive

Flexible:

- Edge profiling (or static prediction)
- Safe (or unsafe)
- Field sensitive (or field insensitive)

Traditional Points-To Graph

```
int x, y, z, *b = &x;
```

```
void foo(int *a) {
```

```
  if(...)
```

```
    b = &y;
```

```
  if(...)
```

```
    a = &z;
```

```
  else(...)
```

```
    a = b;
```

```
  while(...) {
```

```
    x = *a;
```

```
    ...
```

```
  }
```

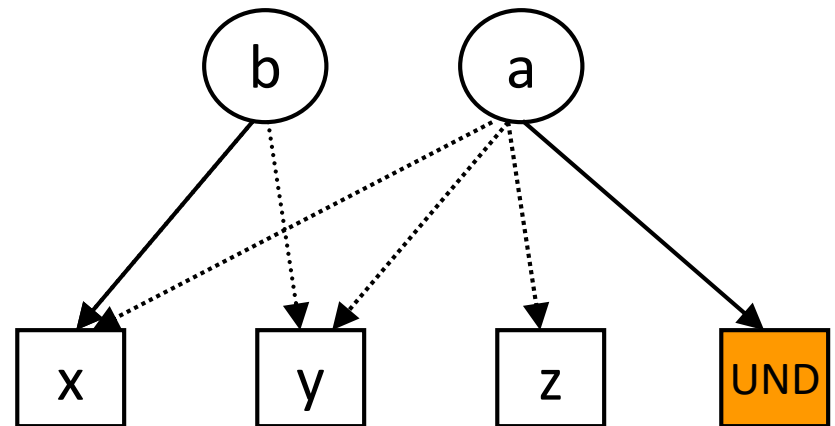
```
}
```

○ = pointer

□ = pointed at

→ = Definitely

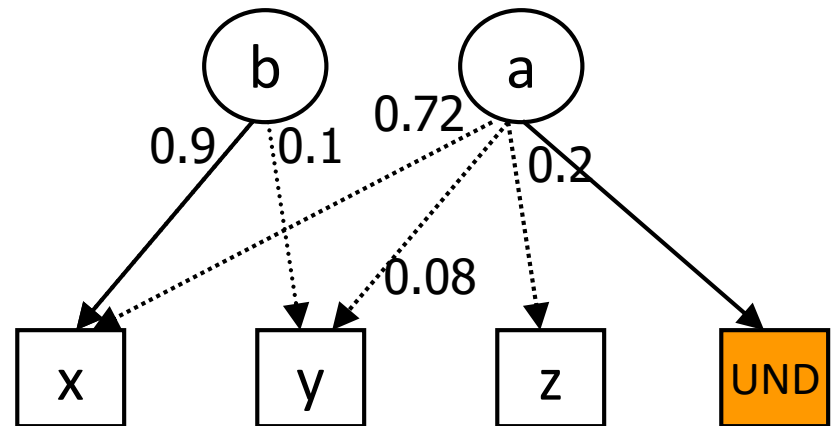
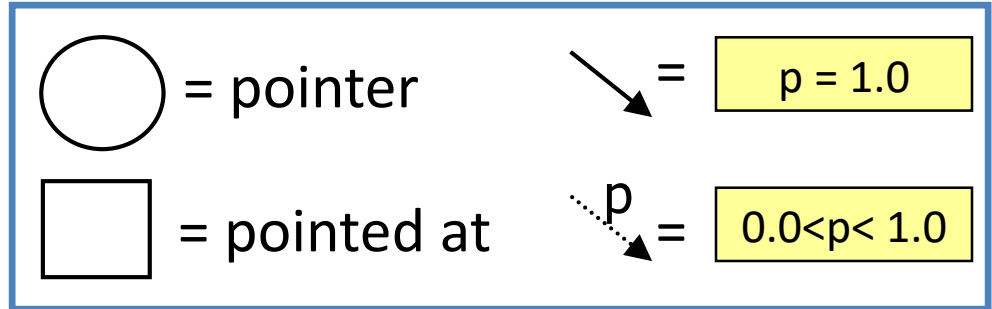
⋯→ = Maybe



Results are inconclusive

Probabilistic Points-To Graph

```
int x, y, z, *b = &x;  
void foo(int *a) {  
    if(...) ⇒0.1 taken(edge profile)  
        b = &y;  
    if(...) ⇒0.2 taken(edge profile)  
        a = &z;  
    else  
        a = b;  
    while(...) {  
        x = *a;  
        ...  
    }  
}
```



Results provide more information

Probabilistic Pointer Analysis Results

Summary

- Matrix-based, transfer function approach
 - SUIF/Matlab implementation
- Scales to the SPECint 95/2000 benchmarks
 - One-level context and flow sensitive
- As accurate as the most precise algorithms
- Interesting result:
 - ~90% of pointers tend to point to only one thing

Pointer Analysis Summary

- Pointers are hard to understand at compile time!
 - accurate analyses are large and complex
- Many different **options**:
 - Representation, heap modeling, aggregate modeling, flow sensitivity, context sensitivity
- Many **algorithms**:
 - Address-taken, Steensgarde, Andersen, Emami
 - BDD-based, probabilistic
- Many **trade-offs**:
 - space, time, accuracy, safety
- Choose the right type of analysis given how the information will be used

CSC D70: Compiler Optimization Memory Optimizations (Intro)

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University of Toronto

Winter 2018

*The content of this lecture is adapted from the lectures of
Todd Mowry and Phillip Gibbons*

Caches: A Quick Review

- How do they work?
- Why do we care about them?
- What are typical configurations today?
- What are some important cache parameters that will affect performance?

Optimizing Cache Performance

- Things to enhance:
 - temporal locality
 - spatial locality
- Things to minimize:
 - conflicts (i.e. bad replacement decisions)

What can the *compiler* do to help?

Two Things We Can Manipulate

- Time:
 - When is an object accessed?
- Space:
 - Where does an object exist in the address space?

How do we exploit these two levers?

Time: Reordering Computation

- What makes it difficult to know *when* an object is accessed?
- How can we predict a *better time* to access it?
 - What information is needed?
- How do we know that this would be *safe*?

Space: Changing Data Layout

- What do we know about an object's **location**?
 - scalars, structures, pointer-based data structures, arrays, code, etc.
- How can we tell what a **better layout** would be?
 - how many can we create?
- To what extent can we **safely** alter the layout?

Types of Objects to Consider

- Scalars
- Structures & Pointers
- Arrays

Scalars

- Locals
- Globals
- Procedure arguments
- Is cache performance a concern here?
- If so, what can be done?

```
int x;  
double y;  
foo(int a) {  
    int i;  
  
    ...  
    x = a*i;  
  
    ...  
}
```

Structures and Pointers

- What can we do here?
 - within a node
 - across nodes

```
struct {  
    int count;  
    double velocity;  
    double inertia;  
    struct node *neighbors[N];  
} node;
```

- What limits the compiler's ability to optimize here?

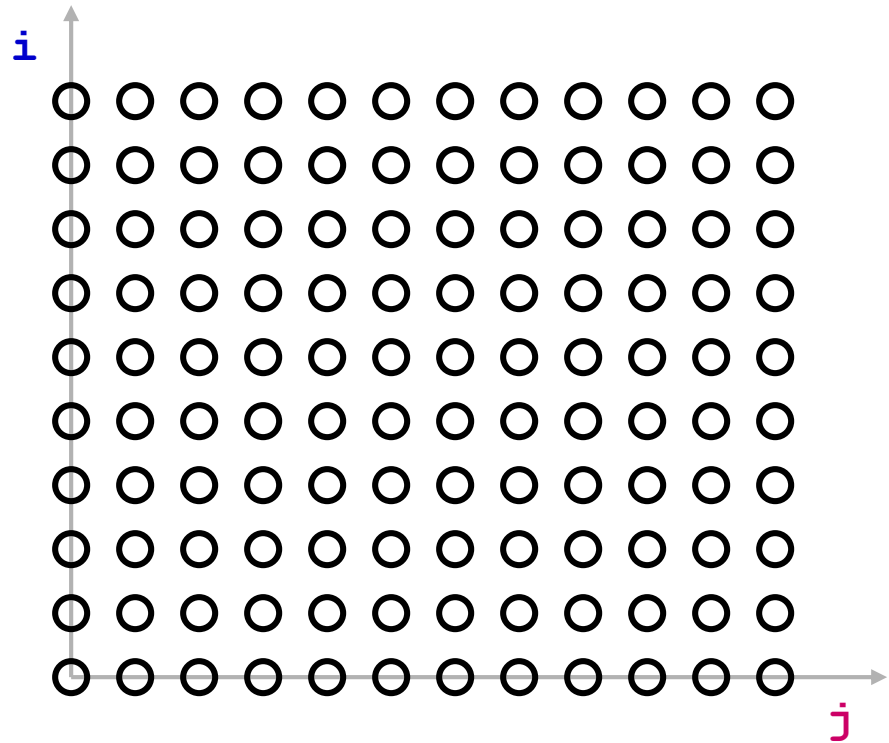
Arrays

```
double A[N][N], B[N][N];  
...  
for i = 0 to N-1  
    for j = 0 to N-1  
        A[i][j] = B[j][i];
```

- usually accessed within **loops nests**
 - makes it easy to understand “time”
- what we know about **array element addresses**:
 - start of array?
 - relative position within array

Handy Representation: “Iteration Space”

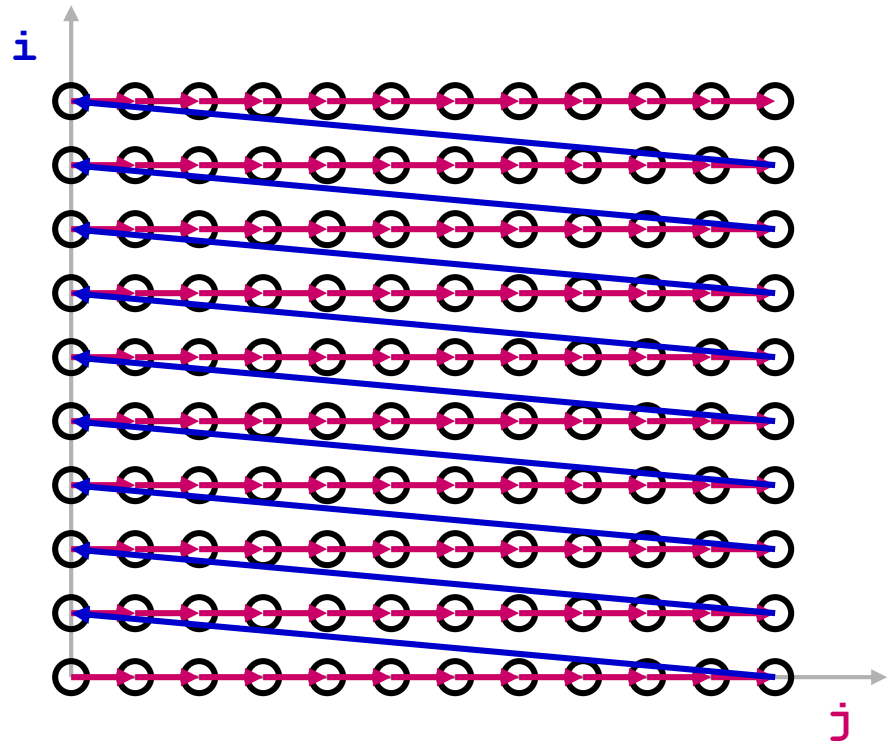
```
for i = 0 to N-1  
  for j = 0 to N-1  
    A[i][j] = B[j][i];
```



- each position represents an iteration

Visitation Order in Iteration Space

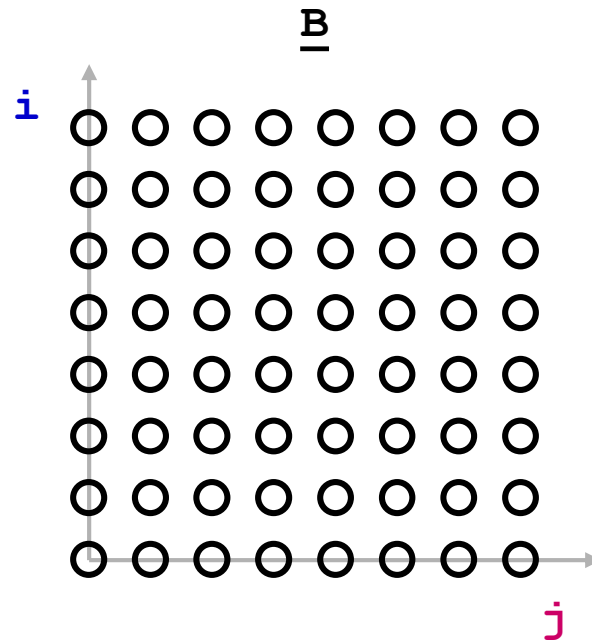
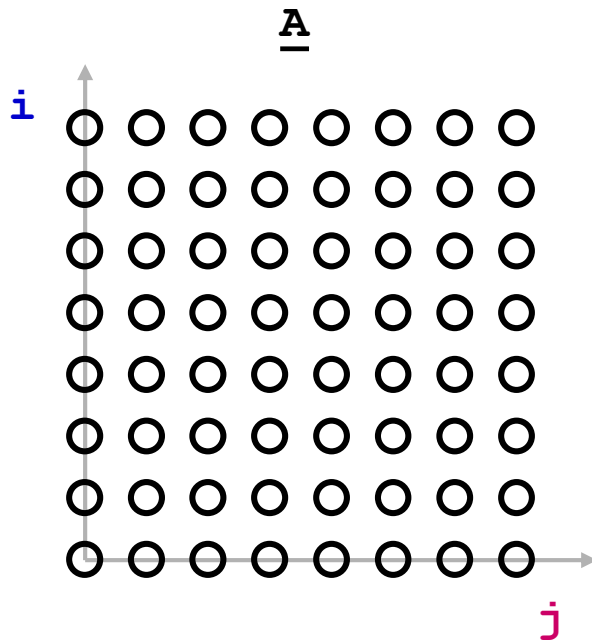
```
for i = 0 to N-1  
  for j = 0 to N-1  
    A[i][j] = B[j][i];
```



- Note: iteration space \neq data space

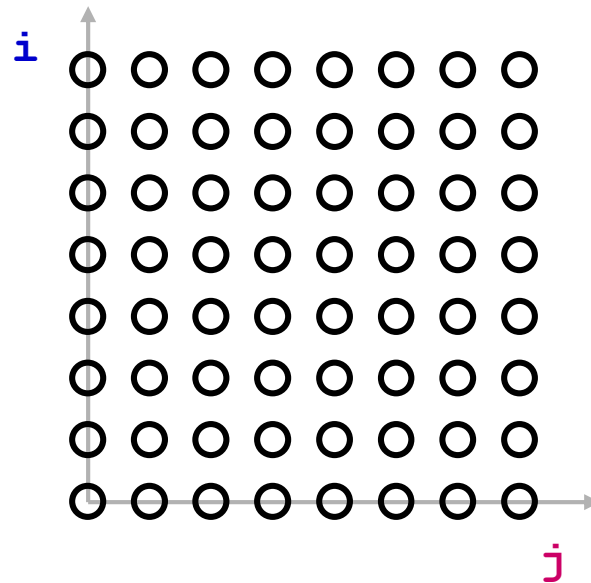
When Do Cache Misses Occur?

```
for i = 0 to N-1  
  for j = 0 to N-1  
    A[i][j] = B[j][i];
```



When Do Cache Misses Occur?

```
for i = 0 to N-1
  for j = 0 to N-1
    A[i+j][0] = i*j;
```



Optimizing the Cache Behavior of Array Accesses

- We need to answer the following questions:
 - when do cache misses occur?
 - use “locality analysis”
 - can we change the order of the iterations (or possibly data layout) to produce better behavior?
 - evaluate the cost of various alternatives
 - does the new ordering/layout still produce correct results?
 - use “dependence analysis”

Examples of Loop Transformations

- Loop Interchange
- Cache Blocking
- Skewing
- Loop Reversal
- ...

(we will briefly discuss the first two next week)

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